

High Speed High Accuracy Linear Hall Sensor

The MH485 is a monolithic programmable Hall sensor IC featuring the planar Hall technology, which is sensitive to the flux density applied orthogonally to the IC surface. The sensor provides an output signal proportional to the applied magnetic flux density and is preferably suited for current measurement.

The transfer characteristic of the MH485 is factory trimmed over temperature, and is programmable (offset, gain) during end-of-line customer calibration. The linear analog output is designed for applications where a very fast response is required, such as inverter applications.

In a typical application, the sensor is used in combination with a soft ferromagnetic core. This core is recommended to be laminated for high bandwidth applications. The Hall IC is placed in a small air gap and the current conductor is passed through the inner part of the ferromagnetic core.

The core concentrates and amplifies the magnetic flux on the Hall sensor IC, which generates an output voltage proportional to the current flowing in the conductor.

Features and Benefits

- End-of-line programmable sensor
- User-selectable internal or external reference voltage
- User-selectable radiometry of QVO
- Sensitivity is independent from V_{DD}
- Measurement range from ± 0.9 to ± 25 mV/G
- Wideband sensing: DC to 200KHz
- Very short response time (<2µs)
- Sensitivity can be custom made
- RoHS compliant
- MSL-1

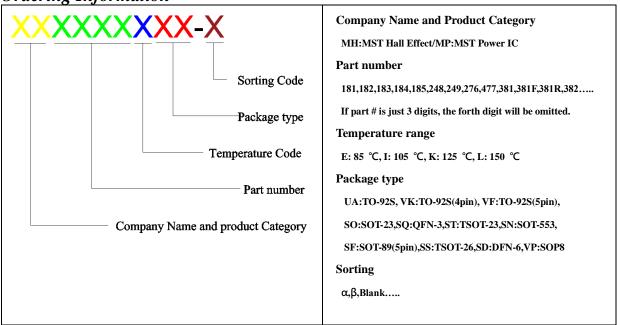
Applications

- High Voltage Traction Motor Inverter
- 48V Boost Recuperation Inverter
- DC/DC Converter
- BLDC motor current monitoring
- Smart Fuse Overcurrent Detection



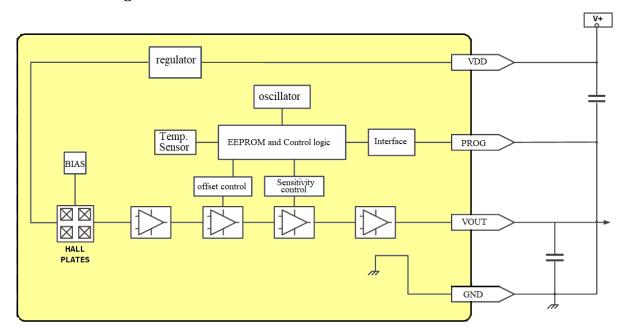
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Ordering Information



Part No.	Temperature Suffix	Package Type
MH485KVP	$K (-40^{\circ}C \text{ to} + 125^{\circ}C)$	VP (SOP8 8PIN)
MH485KVL	$K (-40^{\circ}C \text{ to} + 125^{\circ}C)$	VL (TO-92S 3PIN)

Functional Diagram





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Absolute Maximum Ratings At (Ta=25°C)

Parameter	Symbol	Value	Unit
Positive Supply Voltage (overvoltage)	$V_{ m DD}$	6.5	V
Reverse Voltage	VSrev	-0.3	V
Positive Output Voltage	Vout	5.5	V
Output Sink Current	Isink	-40	mA
Output Source Current	Isource	60	mA
Reverse Output Voltage	VOrev	-0.3	V
Reverse Output Current	IOrev	-50	mA
Operating Ambient Temperature Range	T_{A}	-40 to +125	°C
Storage Temperature Range	T_{S}	-40 to +125	°C
ESD – Human Body Model	ESD _{HBM}	4	KV
Maximum Number of EEPROM Write Cycles	EEPROMW(max)	1000	cycle

Note: Exceeding the absolute maximum ratings may cause permanent damage. Exposure to absolute maximum - rated conditions for extended periods of time may affect device reliability.

General Electrical Specifications

Operating Parameters $T_A = -40$ to 125°C, $V_{DD} = 5V$ or $3.3V \pm 10\%$, unless otherwise specified.

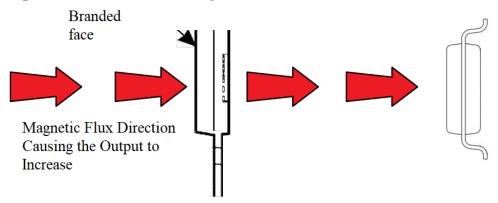
Parameter	Symbol	Test Conditions	Min.	Typ.	Max.	Units
Nominal Supply Voltage	V_{DD}		3/4.5	3.3/5	3.6/5.5	V
Supply Current	Idd	No OUT load		13	18	mA
Output Impedance	Rout	Normal Operation		8		Ω
Output Capacitive Load	C_{L}		1		100	nF
Output Resistive Load	$R_{\rm L}$		4.7			ΚΩ
Linear Output Range	VOLIN	pull-down $\geq 10 \text{ k}\Omega$	10		90	%Vdd

Magnetic specification

Operating Parameters $T_A = -40$ to 125°C, $V_{DD} = 5V$ or $3.3V \pm 10\%$, unless otherwise specified.

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Operational Magnetic Field Range	Вор		±100	±1000	±2300	G
Programmable Sensitivity	S		0.9	2	25	mV/G
Linearity Error (Magnetic)	NL	$\begin{aligned} &V_{OUT} \text{ in } [10\%V_{DD},\\ &90\%V_{DD}],T_A=25^\circ\text{C},RL\\ &\geq 10\;k\Omega \end{aligned}$			±0.25	%FS

Output Behavior versus Magnetic Pole





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Analog output specification

Accuracy specifications

Operating Parameters TA = -40 to $125^{\circ}C$, VDD = 5V or $3.3V \pm 10\%$, unless otherwise specified.

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
RMS Output Noise(high-gain)	Nrms-hg	Values for S=12.5mV/G, 1KHz-100KHz		7		mV _{RMS}
V _{OQ} Ratiometry	$\Delta^{ m R} { m V}$	$V_{DD} = 5V\pm5\%, V_{OQ} = 50\%V_{DD}$		±0.24	±0.4	%V _{OQ}
Temperature coefficient variation of Sensitivity δTCvo		Over full range of BM and TA, calibrated IC, without TC _{OF}	-200		200	ppm/°C
•		Ta = 25°C, after trimming	0.496	0.50	0.504	V
Sensor output Voltage	V_{out}	$V_{DD} = 5V$	2.496	2.50	2.504	V
		$V_{DD} = 5V \text{ or } 3.3V$	0.496	0.5	0.504	V
		$V_{DD} = 5V \text{ or } 3.3V$	VDD/2 -4m	VDD/2	VDD/2 +4m	V
		$V_{DD} = 5V$	VDD/10 -4m	VDD/10	VDD/10 +4m	V
		$V_{DD} = 3.3V$	1.646	1.65	1.654	V
Offset Temperature characteristic	TCVOF	$B_M = 0 \mu T$, $S=12.5 \text{mV/G}$, $V_{OUT} - V_{DD}/2$	-0.120		0.120	mV/°C
Average Fine Sensitivity Programming Step Size	Step _{SENS}	$S=12.5 \text{mV/G}, T_A = 25 ^{\circ}\text{C}$		1.5		μV/G

The accuracy specifications are defined for the factory calibrated sensitivity. The achievable accuracy is dependent on the user's end-of-line calibration.

Timing specifications

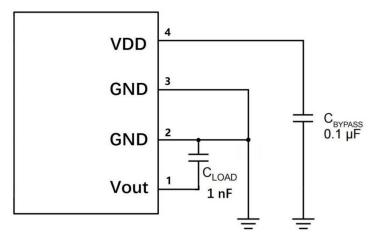
Operating Parameters $T_A = -40$ to $125^{\circ}C$, Vdd = 5V or $3.3V \pm 10\%$, unless otherwise specified.

Parameter	Symbol	Test Conditions	Min	Тур	Max	Units
Response Time	trise	T _A = 25 °C, C _L =1nf, Magnetic field step of 400G, Sens=2mV/G, Measured 90% input to 90% output.		2		μs
Frequency bandwidth	BW	-3 dB, TA = 25 °C	120	170	200	KHz

Programmable Items

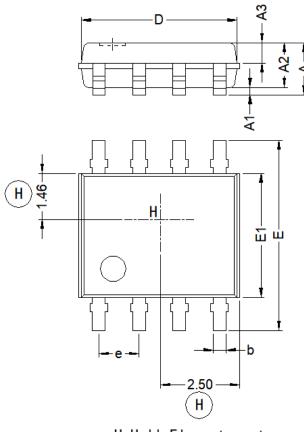
Parameter	Bits	Factory Setting	Comment	
VOQ[4:0]	5	trimmed	Quiescent output level (0 Gauss) adjustment	
RG[4:0]	5	trimmed	Rough gain adjustment	
FG[7:0]	8	trimmed	Fine gain adjustment	
POL	1	0	0: default polarity as described in section 10 (figure 4)	
POL	$\begin{vmatrix} 1 & 0 \end{vmatrix}$		1: opposite polarity	
Vout[2:0]	3	4	0: 0.5V 1:VDD/10 2:1.65V 3: 2.5V 4: VDD/2	

Typical application circuit

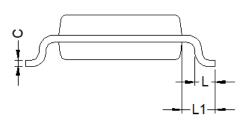


Typical Application

Sensor Location, package dimension and marking VP package Dimension



H:Hall Element center



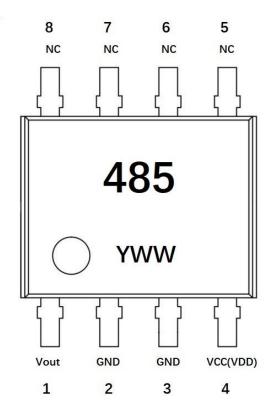
SYMBOL	MILL	IMETE	R	
	MIN	NOM	MAX	
Α			1. 65	
A 1	0. 10		0. 25	
A2	1. 40	1.42	1. 50	
A3	0. 60	0. 65	0. 70	
b	0. 33		0. 47	
С	0. 20		0. 24	
D	4. 80	4. 90	5. 00	
E	5. 90	6. 00	6. 20	
E1	3. 85	3. 90	4. 00	
е	1. 27 (BSC)			
L	0. 50	0. 60	0. 70	
L1	1. 05 (BSC)			

^{*}Strongly recommend: arrange C_{BYPASS} , C_{LOAD} , C_F as close as possible to pin VDD, Vout.



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TOP MARK



NOTES:

- Controlling dimension: mm
- Leads must be free of flash and plating voids
- 3. Do not bend leads within 1 mm of lead to package interface.
- 4. PINOUT:

Pin1 Vout (Sensor Output)

Pin2 GND (Ground)

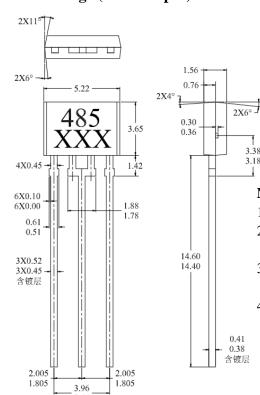
Pin3 GND (Ground)

Pin4 V_{DD} (Supply Voltage)

5. Y=Last digit of year of manufacture

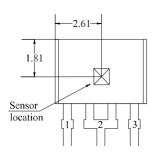
WW=Week of manufacture

VL Package (To-92S-3pin)

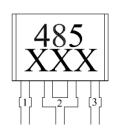


3.66

Hall Chip location



Output Pin Assignment



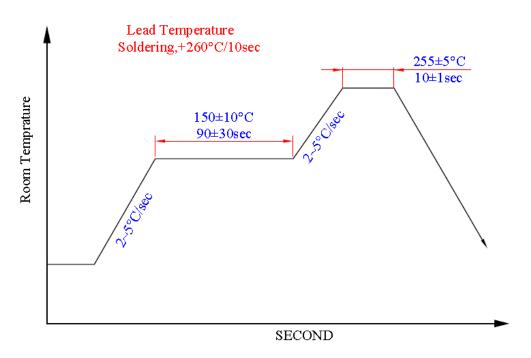
- 1. Controlling dimension: mm
- 2.Leads must be free of flash and plating voids
- 3.Do not bend leads within 1 mm of lead to package interface.
- 4.PINOUT:

NOTES:

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Pin 1 **VOUT** Pin 2 **GND** Pin 3 **VCC**

IR reflow curve



VP/VL Soldering Condition

Packing specification:

Package	Packing Form
SOP8(8pin)	1,000pcs/tube
TO-92S-3PIN	1000pcs/Bag

Inter box label : Size:6cm* 9cm





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Carton label: Size:6cm* 9cm



Combine:

When combine lot, one reel could have two D/C and no more than two DC. One carton could have two devices, no more than two;